



8237/8237-2 HIGH PERFORMANCE PROGRAMMABLE DMA CONTROLLER

- Enable/Disable Control of Individual DMA Requests
- Four Independent DMA Channels
- Independent Autoinitialization of all Channels
- Memory-to-Memory Transfers
- Memory Block Initialization
- Address Increment or Decrement
- High Performance: Transfers up to 1.6M Bytes/Second with 5 MHz 8237-2
- Directly Expandable to any Number of Channels
- End of Process Input for Terminating Transfers
- Software DMA Requests
- Independent Polarity Control for DREQ and DACK Signals

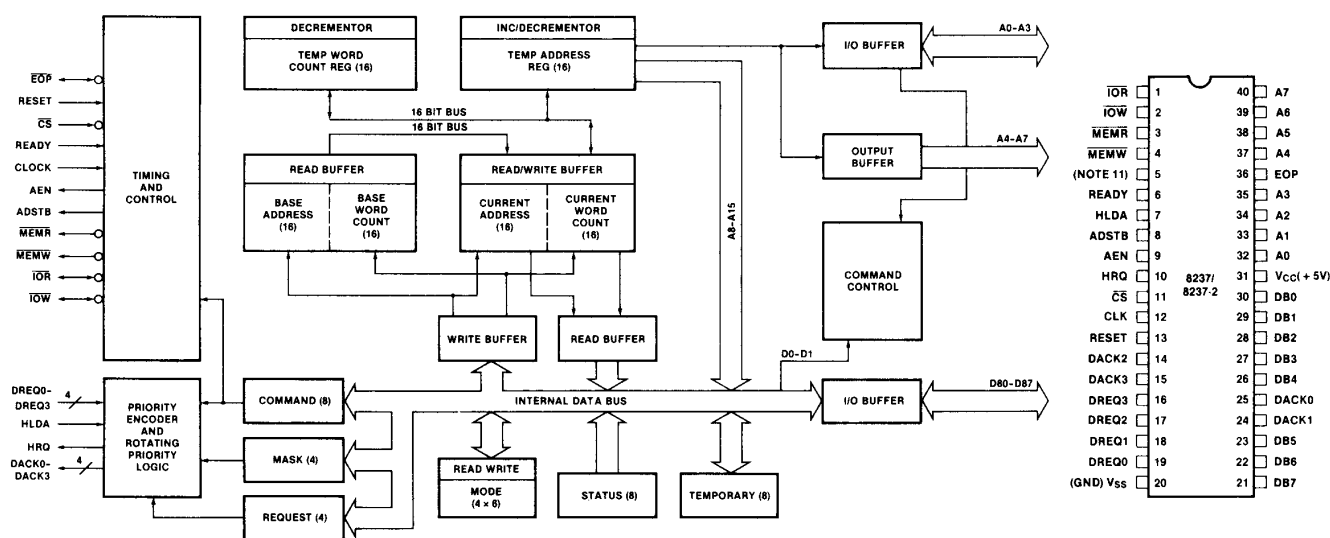
The 8237 Multimode Direct Memory Access (DMA) Controller is a peripheral interface circuit for microprocessor systems. It is designed to improve system performance by allowing external devices to directly transfer information to or from the system memory. Memory-to-memory transfer capability is also provided. The 8237 offers a wide variety of programmable control features to enhance data throughput and system optimization and to allow dynamic reconfiguration under program control.

The 8237 is designed to be used in conjunction with an external 8-bit address register such as the 8282. It contains four independent channels and may be expanded to any number of channels by cascading additional controller chips.

The three basic transfer modes allow programmability of the types of DMA service by the user. Each channel can be individually programmed to Autoinitialize to its original condition following an End of Process (EOP).

Each channel has a full 64K address and word count capability.

The 8237-2 is a 5 MHz selected version of the standard 3 MHz 8237.



BLOCK DIAGRAM

Figure 1. Pin Configuration

PIN DEFINITIONS

V_{CC}: +5 volt supply

V_{SS}: Ground

CLK (Clock, Input)

This input controls the internal operations of the 8237 and its rate of data transfers. The input may be driven at up to 3 MHz for the standard 8237 and up to 5 MHz for the 8237-2.

\overline{CS} (Chip Select, Input)

Chip Select is an active low input used to select the 8237 as an I/O device during the Idle cycle. This allows CPU communication on the data bus.

RESET (Reset, Input)

Reset is an asynchronous active high input which clears the Command, Status, Request and Temporary registers. It also clears the first/last flip/flop and sets the Mask register. Following a Reset the device is in the Idle cycle.

READY (Ready, Input)

Ready is an input used to extend the memory read and write pulses from the 8237 to accommodate slow memories or I/O peripheral devices.

HLDA (Hold Acknowledge, Input)

The active high Hold Acknowledge from the CPU indicates that control of the system buses have been relinquished.

DREQ0–DREQ3 (DMA Request, Input)

The DMA Request lines are individual asynchronous channel request inputs used by peripheral circuits to obtain DMA service. In Fixed Priority, DREQ0 has the highest priority and DREQ3 has the lowest priority. A request is generated by activating the DREQ line of a channel. DACK will acknowledge the recognition of DREQ signal. Polarity of DREQ is programmable. Reset initializes these lines to active high. DREQ must be maintained until the corresponding DACK goes active.

DB0–DB7 (Data Bus, Input/Output)

The Data Bus lines are bidirectional three-state signals connected to the system data bus. The outputs are enabled in the Program Condition during the I/O Read to output the contents of an Address register, a Status register, the Temporary register or a Word Count register to the CPU. The outputs are disabled and the inputs are read during an I/O Write cycle when the CPU is programming the 8237 control registers. During DMA cycles the most significant 8 bits of the address are output onto the data bus to be strobed into an external latch by ADSTB. In memory-to-memory operations, data from the memory comes into the 8237 on the data bus during the read-from-memory transfer. In the write-to-memory transfer, the data bus outputs place the data into the new memory location.

\overline{IOR} (I/O Read, Input/Output)

I/O Read is a bidirectional active low three-state line. In the Idle cycle, it is an input control signal used by the CPU to read the control registers. In the Active cycle, it is an output control signal used by the 8237 to access data from a peripheral during a DMA Write transfer.

\overline{IOW} (I/O Write, Input/Output)

I/O Write is a bidirectional active low three-state line. In the Idle cycle, it is an input control signal used by the CPU to load information into the 8237. In the Active cycle, it is an output control signal used by the 8237 to load data to the peripheral during a DMA Read transfer.

\overline{EOP} (End of Process, Input/Output)

\overline{EOP} is an active low bidirectional signal. Information concerning the completion of DMA services is available at the bidirectional \overline{EOP} pin. The 8237 allows an external signal to terminate an active DMA service. This is accomplished by pulling the \overline{EOP} input low with an external \overline{EOP} signal. The 8237 also generates a pulse when the terminal count (TC) for any channel is reached. This generates an \overline{EOP} signal which is output through the \overline{EOP} Line. The reception of \overline{EOP} , either internal or external, will cause the 8237 to terminate the service, reset the request, and, if Autoinitialize is enabled, to write the base registers to the current registers of that channel. The mask bit and TC bit in the status word will be set for the currently active channel by \overline{EOP} unless the channel is programmed for Autoinitialize. In that case, the mask bit remains clear. During memory-to-memory transfers, \overline{EOP} will be output when the TC for channel 1 occurs. \overline{EOP} should be tied high with a pull-up resistor if it is not used to prevent erroneous end of process inputs.

A0–A3 (Address, Input/Output)

The four least significant address lines are bidirectional three-state signals. In the Idle cycle they are inputs and are used by the 8237 to address the control register to be loaded or read. In the Active cycle they are outputs and provide the lower 4 bits of the output address.

A4–A7 (Address, Output)

The four most significant address lines are three-state outputs and provide 4 bits of address. These lines are enabled only during the DMA service.

HRQ (Hold Request, Output)

This is the Hold Request to the CPU and is used to request control of the system bus. If the corresponding mask bit is clear, the presence of any valid DREQ causes the 8237 to issue the HRQ. After HRQ goes active at least one clock cycle (TCY) must occur before HLDA goes active.

DACK0–DACK3 (DMA Acknowledge, Output)

DMA Acknowledge is used to notify the individual peripherals when one has been granted a DMA cycle. The sense of these lines is programmable. Reset initializes them to active low.

AEN (Address Enable, Output)

This output enables the 8-bit latch containing the upper 8 address bits onto the system address bus. AEN can also be used to disable other system bus drivers during DMA transfers. AEN is active HIGH.

ADSTB (Address Strobe, Output)

The active high Address Strobe is used to strobe the upper address byte into an external latch.

MEMR (Memory Read, Output)

The Memory Read signal is an active low three-state output used to access data from the selected memory location during a DMA Read or a memory-to-memory transfer.

MEMW (Memory Write, Output)

The Memory Write signal is an active low three-state output used to write data to the selected memory location during a DMA Write or a memory-to-memory transfer.

FUNCTIONAL DESCRIPTION

The 8237 block diagram includes the major logic blocks and all of the internal registers. The data interconnection paths are also shown. Not shown are the various control signals between the blocks. The 8237 contains 344 bits of internal memory in the form of registers. Figure 2 lists these registers by name and shows the size of each. A detailed description of the registers and their functions can be found under Register Description.

Name	Size	Number
Base Address Registers	16 bits	4
Base Word Count Registers	16 bits	4
Current Address Registers	16 bits	4
Current Word Count Registers	16 bits	4
Temporary Address Register	16 bits	1
Temporary Word Count Register	16 bits	1
Status Register	8 bits	1
Command Register	8 bits	1
Temporary Register	8 bits	1
Mode Registers	6 bits	4
Mask Register	4 bits	1
Request Register	4 bits	1

Figure 2. 8237 Internal Registers

The 8237 contains three basic blocks of control logic. The Timing Control block generates internal timing and external control signals for the 8237. The Program Command Control block decodes the various commands given to the 8237 by the microprocessor prior to servicing a DMA Request. It also decodes the Mode Control word used to select the type of DMA during the servicing. The Priority Encoder block resolves priority contention between DMA channels requesting service simultaneously.

The Timing Control block derives internal timing from the clock input. In 8237 systems this input will usually be the $\phi 2$ TTL clock from an 8224 or CLK from an 8085A. However, any appropriate system clock will suffice.

DMA OPERATION

The 8237 is designed to operate in two major cycles. These are called Idle and Active cycles. Each device cycle is made up of a number of states. The 8237 can assume seven separate states, each composed of one full clock period. State I (SI) is the inactive state. It is entered when the 8237 has no valid DMA requests pending. While in SI, the DMA controller is inactive but may be in the Program Condition, being programmed by the processor. State O (SO) is the first state of a DMA service. The 8237 has requested a hold but the processor has not yet returned an acknowledge. An acknowledge from the CPU will signal that transfers may begin. S1, S2, S3 and S4 are the working states of the DMA service. If more time is needed to complete a transfer than is available with normal timing, wait states (SW) can be inserted between S2 or S3 and S4 by the use of the Ready line on the 8237.

Memory-to-memory transfers require a read-from and a write-to-memory to complete each transfer. The states, which resemble the normal working states, use two digit numbers for identification. Eight states are required for a single transfer. The first four states (S11, S12, S13, S14) are used for the read-from-memory half and the last four states (S21, S22, S23, S24) for the write-to-memory half of the transfer.

IDLE CYCLE

When no channel is requesting service, the 8237 will enter the Idle cycle and perform "SI" states. In this cycle the 8237 will sample the DREQ lines every clock cycle to determine if any channel is requesting a DMA service. The device will also sample \overline{CS} , looking for an attempt by the microprocessor to write or read the internal registers of the 8237. When \overline{CS} is low and HRQ is low, the 8237 enters the Program Condition. The CPU can now establish, change or inspect the internal definition of the part by reading from or writing to the internal registers. Address lines A0-A3 are inputs to the device and select which registers will be read or written. The \overline{IOR} and \overline{IOW} lines are used to select and time reads or writes. Due to the number and size of the internal registers, an internal flip-flop is used to generate an additional bit of address. This bit is used to determine the upper or lower byte of the 16-bit Address and Word Count registers. The flip-flop is reset by Master Clear or Reset. A separate software command can also reset this flip-flop.

Special software commands can be executed by the 8237 in the Program Condition. These commands are decoded as sets of addresses with the \overline{CS} and \overline{IOW} . The commands do not make use of the data bus. Instructions include Clear First/Last Flip-flop and Master Clear.

ACTIVE CYCLE

When the 8237 is in the Idle cycle and a channel requests a DMA service, the device will output an HRQ to the microprocessor and enter the Active cycle. It is in this cycle that the DMA service will take place, in one of four modes:

Single Transfer Mode — In Single Transfer mode the device is programmed to make one transfer only. The

word count will be decremented and the address decremented or incremented following each transfer. When the word count goes to zero, a Terminal Count (TC) will cause an Autoinitialize if the channel has been programmed to do so.

DREQ must be held active until DACK becomes active in order to be recognized. If DREQ is held active throughout the single transfer, HRQ will go inactive and release the bus to the system. It will again go active and, upon receipt of a new HLDA, another single transfer will be performed. In 8080A/8085A systems this will ensure one full machine cycle execution between DMA transfers. Details of timing between the 8237 and other bus control protocols will depend upon the characteristics of the microprocessor involved.

Block Transfer Mode — In Block Transfer mode the device is activated by DREQ to continue making transfers during the service until a TC, caused by word count going to zero, or an external End of Process (EOP) is encountered. DREQ need only be held active until DACK becomes active. Again, an Autoinitialization will occur at the end of the service if the channel has been programmed for it.

Demand Transfer Mode — In Demand Transfer mode the device is programmed to continue making transfers until a TC or external $\overline{\text{EOP}}$ is encountered or until DREQ goes inactive. Thus transfers may continue until the I/O device has exhausted its data capacity. After the I/O device has had a chance to catch up, the DMA service is re-established by means of a DREQ. During the time between services when the microprocessor is allowed to operate, the intermediate values of address and word count are stored in the 8237 Current Address and Current Word Count registers. Only an $\overline{\text{EOP}}$ can cause an Autoinitialize at the end of the service. $\overline{\text{EOP}}$ is generated either by TC or by an external signal.

Cascade Mode — This mode is used to cascade more than one 8237 together for simple system expansion. The HRQ and HLDA signals from the additional 8237 are connected to the DREQ and DACK signals of a channel of the initial 8237. This allows the DMA requests of the additional device to propagate through the priority network circuitry of the preceding device. The priority chain is preserved and the new device must wait for its turn to acknowledge requests. Since the cascade channel in the initial device is used only for prioritizing the additional device, it does not output any address or control signals of its own. These would conflict with the outputs of the active channel in the added device. The 8237 will respond to DREQ and DACK but all other outputs except HRQ will be disabled.

Figure 3 shows two additional devices cascaded into an initial device using two of the previous channels. This forms a two level DMA system. More 8237s could be added at the second level by using the remaining channels of the first level. Additional devices can also be added by cascading into the channels of the second level devices, forming a third level.

TRANSFER TYPES

Each of the three active transfer modes can perform three different types of transfers. These are Read, Write

and Verify. Write transfers move data from an I/O device to the memory by activating $\overline{\text{MEMW}}$ and $\overline{\text{IOR}}$. Read transfers move data from memory to an I/O device by activating $\overline{\text{MEMR}}$ and $\overline{\text{IOW}}$. Verify transfers are pseudo transfers. The 8237 operates as in Read or Write transfers generating addresses, and responding to EOP, etc. However, the memory and I/O control lines all remain inactive.

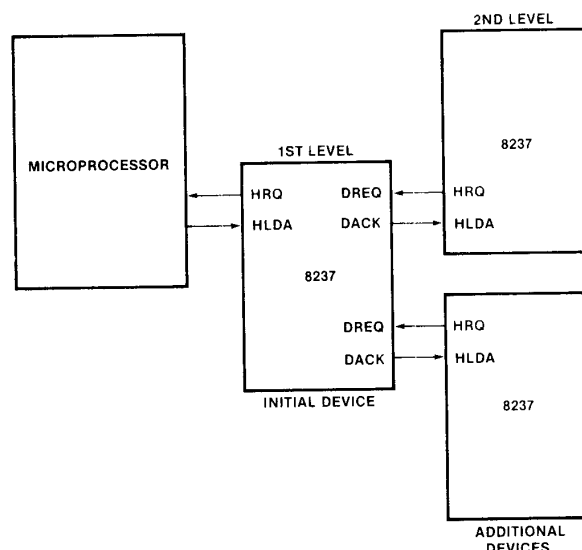


Figure 3. Cascaded 8237s

Memory-to-Memory — To perform block moves of data from one memory address space to another with a minimum of program effort and time, the 8237 includes a memory-to-memory transfer feature. Programming a bit in the Command register selects channels 0 and 1 to operate as memory-to-memory transfer channels. The transfer is initiated by setting the software DREQ for channel 0. The 8237 requests a DMA service in the normal manner. After HLDA is true, the device, using eight-state transfers in Block Transfer mode, reads data from the memory. The channel 0 Current Address register is the source for the address used and is decremented or incremented in the normal manner. The data byte read from the memory is stored in the 8237 internal Temporary register. Channel 1 then writes the data from the Temporary register to memory using the address in its Current Address register and incrementing or decrementing it in the normal manner. The channel 1 Current Word Count is decremented. When the word count of channel 1 goes to zero, a TC is generated causing an $\overline{\text{EOP}}$ output, terminating the service.

Channel 0 may be programmed to retain the same address for all transfers. This allows a single word to be written to a block of memory.

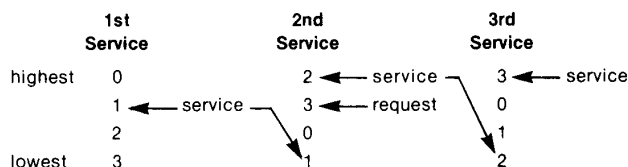
The 8237 will respond to external $\overline{\text{EOP}}$ signals during memory-to-memory transfers. Data comparators in block search schemes may use this input to terminate the service when a match is found. The timing of memory-to-memory transfers is found in Diagram 4. Memory-to-memory operations can be detected as an active AEN with no DACK outputs.

Autoinitialize — By programming a bit in the Mode register, a channel may be set up as an Autoinitialize

channel. During Autoinitialize initialization, the original values of the Current Address and Current Word Count registers are automatically restored from the Base Address and Base Word Count registers of that channel following EOP. The base registers are loaded simultaneously with the current registers by the microprocessor and remain unchanged throughout the DMA service. The mask bit is not set when the channel is in Autoinitialize. Following Autoinitialize the channel is ready to perform another service without CPU intervention.

Priority — The 8237 has two types of priority encoding available as software selectable options. The first is Fixed Priority which fixes the channels in priority order based upon the descending value of their number. The channel with the lowest priority is 3 followed by 2, 1 and the highest priority channel, 0. After the recognition of any one channel for service, the other channels are prevented from interfering with that service until it is completed.

The second scheme is Rotating Priority. The last channel to get service becomes the lowest priority channel with the others rotating accordingly.



With Rotating Priority in a single chip DMA system, any device requesting service is guaranteed to be recognized after no more than three higher priority services have occurred. This prevents any one channel from monopolizing the system.

Compressed Timing — In order to achieve even greater throughput where system characteristics permit, the 8237 can compress the transfer time to two clock cycles. From Timing Diagram 3 it can be seen that state S3 is used to extend the access time of the read pulse. By removing state S3, the read pulse width is made equal to the write pulse width and a transfer consists only of state S2 to change the address and state S4 to perform the read/write. S1 states will still occur when A8-A15 need updating (see Address Generation). Timing for compressed transfers is found in Diagram 6.

Address Generation — In order to reduce pin count, the 8237 multiplexes the eight higher order address bits on the data lines. State S1 is used to output the higher order address bits to an external latch from which they may be placed on the address bus. The falling edge of Address Strobe (ADSTB) is used to load these bits from the data lines to the latch. Address Enable (AEN) is used to enable the bits onto the address bus through a three-state enable. The lower order address bits are output by the 8237 directly. Lines A0-A7 should be connected to the address bus. Timing Diagram 3 shows the time relationships between CLK, AEN, ADSTB, DB0-DB7 and A0-A7.

During Block and Demand Transfer mode services, which include multiple transfers, the addresses generated will be sequential. For many transfers the data held in the external address latch will remain the same. This data need only change when a carry or borrow from A7 to A8 takes place in the normal sequence of addresses. To save time and speed transfers, the 8237 executes S1 states only when updating of A8-A15 in the latch is necessary. This means for long services, S1 states may occur only once every 256 transfers, a savings of 255 clock cycles for each 256 transfers.

REGISTER DESCRIPTION

Current Address Register — Each channel has a 16-bit Current Address register. This register holds the value of the address used during DMA transfers. The address is automatically incremented or decremented after each transfer and the intermediate values of the address are stored in the Current Address register during the transfer. This register is written or read by the microprocessor in successive 8-bit bytes. It may also be reinitialized by an Autoinitialize back to its original value. Autoinitialize takes place only after an EOP.

Current Word Register — Each channel has a 16-bit Current Word Count register. This register holds the number of transfers to be performed. The word count is decremented after each transfer. The intermediate value of the word count is stored in the register during the transfer. When the value in the register goes to zero, a TC will be generated. This register is loaded or read in successive 8-bit bytes by the microprocessor in the Program Condition. Following the end of a DMA service it may also be reinitialized by an Autoinitialization back to its original value. Autoinitialize can occur only when an EOP occurs.

Base Address and Base Word Count Registers — Each channel has a pair of Base Address and Base Word Count registers. These 16-bit registers store the original value of their associated current registers. During Autoinitialize these values are used to restore the current registers to their original values. The base registers are written simultaneously with their corresponding current register in 8-bit bytes in the Program Condition by the microprocessor. These registers cannot be read by the microprocessor.

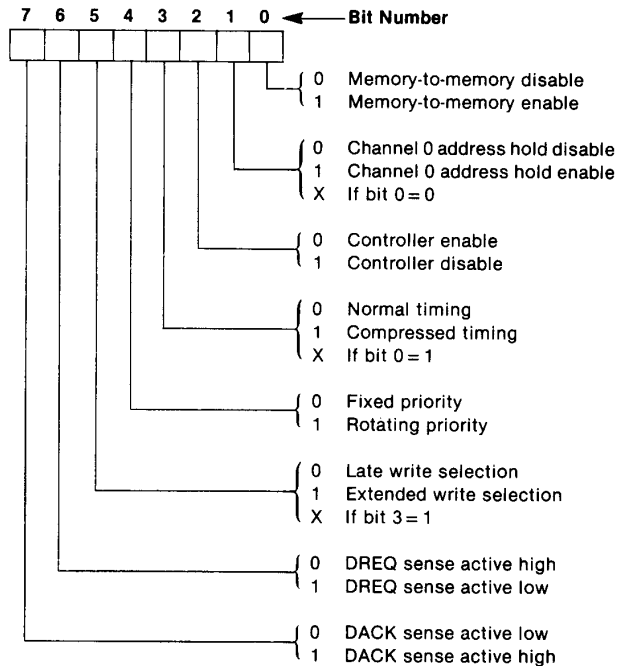
Command Register — This 8-bit register controls the operation of the 8237. It is programmed by the microprocessor in the Program Condition and is cleared by Reset. The following table lists the function of the command bits. See Figure 6 for address coding.

Mode Register — Each channel has a 6-bit Mode register associated with it. When the register is being written to by the microprocessor in the Program Condition, bits 0 and 1 determine which channel Mode register is to be written.

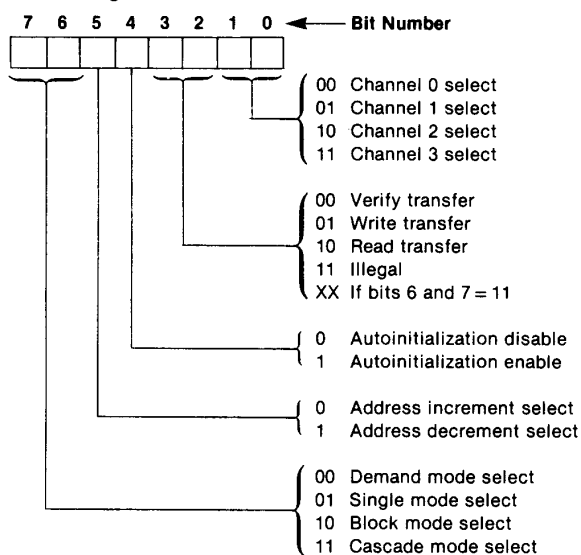
Request Register — The 8237 can respond to requests for DMA service which are initiated by software as well as by a DREQ. Each channel has a request bit associated with it in the 4-bit Request register. These are non-

maskable and subject to prioritization by the Priority Encoder network. Each register bit is set or reset separately under software control or is cleared upon generation of a TC or external \overline{EOP} . The entire register is cleared by a Reset. To set or reset a bit, the software loads the proper form of the data word. See Figure 4 for address coding.

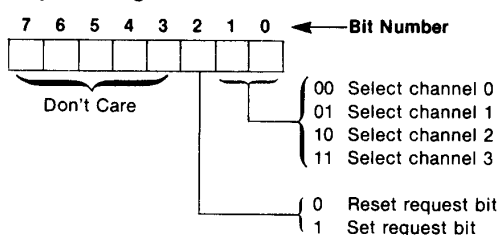
Command Register



Mode Register

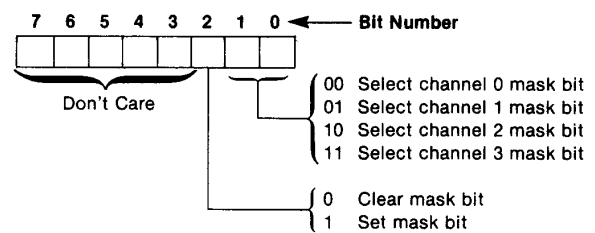


Request Register

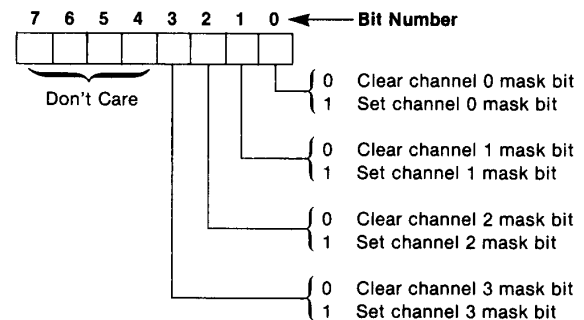


Software requests will be serviced only if the channel is in Block mode. When initiating a memory-to-memory transfer, the software request for channel 0 should be set.

Mask Register — Each channel has associated with it a mask bit which can be set to disable the incoming DREQ. Each mask bit is set when its associated channel produces an \overline{EOP} if the channel is not programmed for Autoinitialize. Each bit of the 4-bit Mask register may also be set or cleared separately under software control. The entire register is also set by a Reset. This disables all DMA requests until a clear Mask register instruction allows them to occur. The instruction to separately set or clear the mask bits is similar in form to that used with the Request register. See Figure 4 for instruction addressing.



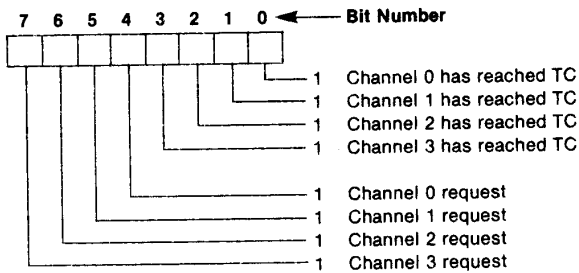
All four bits of the Mask register may also be written with a single command.



Register	Operation	Signals						
		CS	IOR	IOW	A3	A2	A1	A0
Command	Write	0	1	0	1	0	0	0
Mode	Write	0	1	0	1	0	1	1
Request	Write	0	1	0	1	0	0	1
Mask	Set/Reset	0	1	0	1	0	1	0
Mask	Write	0	1	0	1	1	1	1
Temporary	Read	0	0	1	1	1	0	1
Status	Read	0	0	1	1	0	0	0

Figure 4. Definition of Register Codes

Status Register — The Status register is available to be read out of the 8237 by the microprocessor. It contains information about the status of the devices at this point. This information includes which channels have reached a terminal count and which channels have pending DMA requests. Bits 0-3 are set every time a TC is reached by that channel or an external \overline{EOP} is applied. These bits are cleared upon Reset and on each Status Read. Bits 4-7 are set whenever their corresponding channel is requesting service.



Temporary Register — The Temporary register is used to hold data during memory-to-memory transfers. Following the completion of the transfers, the last word moved can be read by the microprocessor in the Program Condition. The Temporary register always contains the last byte transferred in the previous memory-to-memory operation, unless cleared by a Reset.

Software Commands — These are additional special software commands which can be executed in the Program Condition. They do not depend on any specific bit pattern on the data bus. The two software commands are:

Clear First/Last Flip-Flop: This command is executed prior to writing or reading new address or word count information to the 8237. This initializes the flip-flop to a known state so that subsequent accesses to register contents by the microprocessor will address upper and lower bytes in the correct sequence.

Master Clear: This software instruction has the same effect as the hardware Reset. The Command, Status, Request, Temporary, and Internal First/Last Flip-Flop registers are cleared and the Mask register is set. The 8237 will enter the Idle cycle.

Figure 5 lists the address codes for the software commands:

Signals						Operation
A3	A2	A1	A0	$\overline{\text{IOR}}$	$\overline{\text{IOW}}$	
1	0	0	0	0	1	Read Status Register
1	0	0	0	1	0	Write Command Register
1	0	0	1	0	1	Illegal
1	0	0	1	1	0	Write Request Register
1	0	1	0	0	1	Illegal
1	0	1	0	1	0	Write Single Mask Register Bit
1	0	1	1	0	1	Illegal
1	0	1	1	1	0	Write Mode Register
1	1	0	0	0	1	Illegal
1	1	0	0	1	0	Clear Byte Pointer Flip/Flop
1	1	0	1	0	1	Read Temporary Register
1	1	0	1	1	0	Master Clear
1	1	1	0	0	1	Illegal
1	1	1	0	1	0	Illegal
1	1	1	1	0	1	Illegal
1	1	1	1	1	0	Write All Mask Register Bits

Figure 5. Software Command Codes

Channel	Register	Operation	Signals							Internal Flip-Flop	Data Bus DB0-DB7	
			CS	IOR	IOW	A3	A2	A1	A0			
0	Base and Current Address	Write	0	1	0	0	0	0	0	0	0	A0-A7
			0	1	0	0	0	0	0	0	1	A8-A15
	Current Address	Read	0	0	1	0	0	0	0	0	0	A0-A7
			0	0	1	0	0	0	0	0	1	A8-A15
	Base and Current Word Count	Write	0	1	0	0	0	0	1	0	W0-W7	
			0	1	0	0	0	0	1	1	W8-W15	
	Current Word Count	Read	0	0	1	0	0	0	1	0	W0-W7	
			0	0	1	0	0	0	1	1	W8-W15	
1	Base and Current Address	Write	0	1	0	0	0	1	0	0	A0-A7	
			0	1	0	0	0	1	1	0	1	A8-A15
	Current Address	Read	0	0	1	0	0	1	0	0	A0-A7	
			0	0	1	0	0	1	0	1	1	A8-A15
	Base and Current Word Count	Write	0	1	0	0	0	1	1	0	W0-W7	
			0	1	0	0	0	1	1	1	1	W8-W15
	Current Word Count	Read	0	0	1	0	0	1	1	0	W0-W7	
			0	0	1	0	0	1	1	1	1	W8-W15
2	Base and Current Address	Write	0	1	0	0	1	0	0	0	A0-A7	
			0	1	0	0	1	0	0	1	1	A8-A15
	Current Address	Read	0	0	1	0	1	0	0	0	0	A0-A7
			0	0	1	0	1	0	0	1	1	A8-A15
	Base and Current Word Count	Write	0	1	0	0	1	0	1	0	0	W0-W7
			0	1	0	0	1	0	1	1	1	W8-W15
	Current Word Count	Read	0	0	1	0	1	0	1	0	0	W0-W7
			0	0	1	0	1	0	1	1	1	W8-W15
3	Base and Current Address	Write	0	1	0	0	1	1	0	0	A0-A7	
			0	1	0	0	1	1	0	1	1	A8-A15
	Current Address	Read	0	0	1	0	1	1	0	0	A0-A7	
			0	0	1	0	1	1	0	1	1	A8-A15
	Base and Current Word Count	Write	0	1	0	0	1	1	1	0	W0-W7	
			0	1	0	0	1	1	1	1	1	W8-W15
	Current Word Count	Read	0	0	1	0	1	1	1	0	W0-W7	
			0	0	1	0	1	1	1	1	1	W8-W15

Figure 6. Word Count and Address Register Command Codes

APPLICATION INFORMATION

Figure 7 shows a convenient method for configuring a DMA system with the 8237 controller and an 8080A/8085A microprocessor system. The multimode DMA controller issues a HRQ to the processor whenever there is at least one valid DMA request from a peripheral device. When the processor replies with a HLDA signal, the 8237 takes control of the address bus, the data bus and the control bus. The address for the

first transfer operation comes out in two bytes — the least significant 8 bits on the eight address outputs and the most significant 8 bits on the data bus. The contents of the data bus are then latched into the 8282 8-bit latch to complete the full 16 bits of the address bus. The 8282 is a high speed, 8-bit, three-state latch in a 20-pin package. After the initial transfer takes place, the latch is updated only after a carry or borrow is generated in the least significant address byte. Four DMA channels are provided when one 8237 is used.

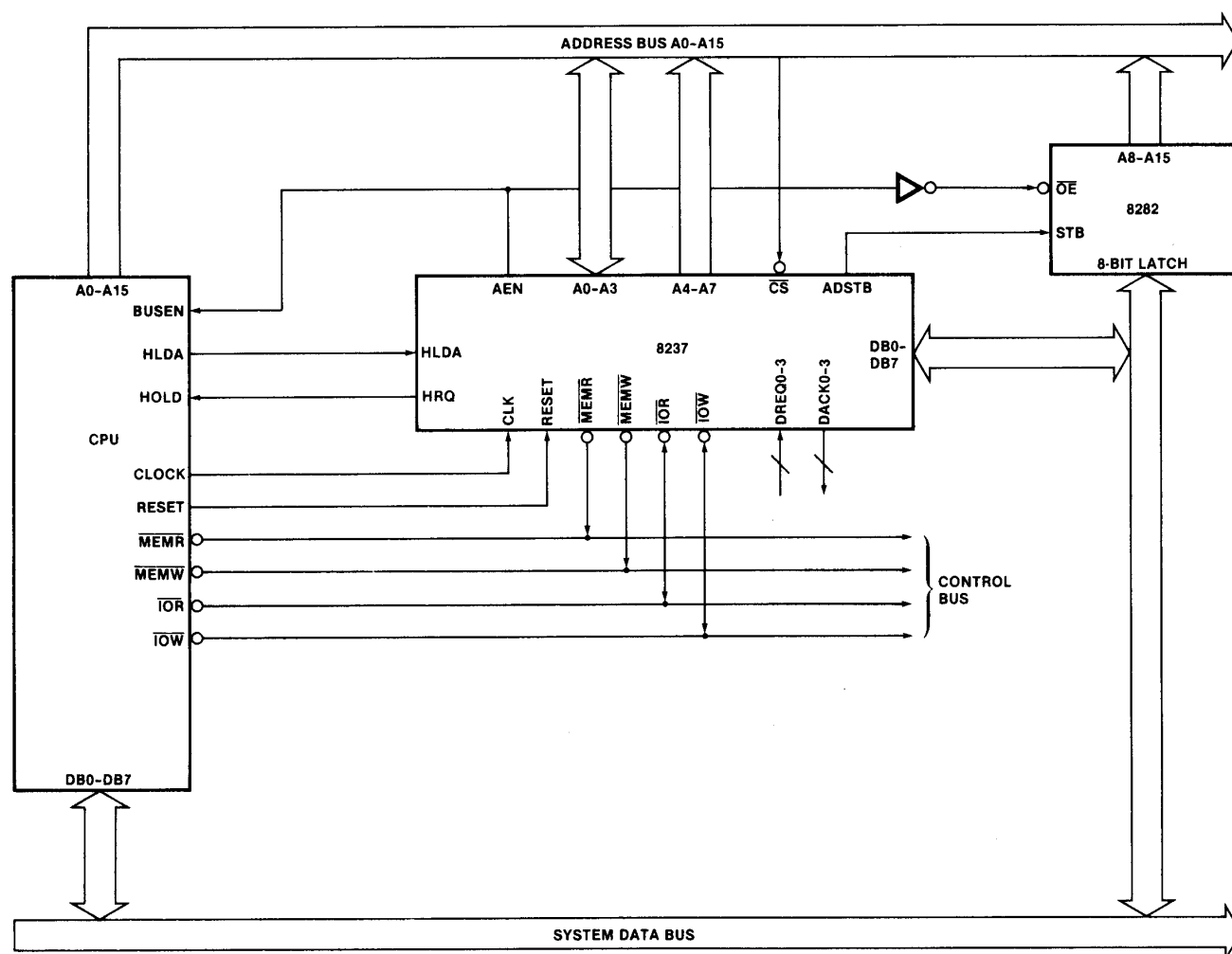


Figure 7. 8237 System Interface

ABSOLUTE MAXIMUM RATINGS*

Ambient Temperature under Bias 0°C to 70°C
 Storage Temperature – 65°C to + 150°C
 Voltage on any Pin with
 Respect to Ground – 0.5 to 7V
 Power Dissipation 1.5 Watt

*COMMENT: Stresses above those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

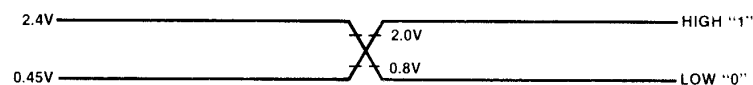
D.C. CHARACTERISTICS

$T_A = 0^\circ\text{C}$ to 70°C , $V_{CC} = 5.0\text{V} \pm 5\%$, $GND = 0\text{V}$

Symbol	Parameter	Min.	Typ. ⁽¹⁾	Max.	Unit	Test Conditions
V_{OH}	Output HIGH Voltage	2.4			V	$I_{OH} = -200\ \mu\text{A}$
		3.3			V	$I_{OH} = -100\ \mu\text{A}$ (HRQ Only)
V_{OL}	Output LOW Voltage			0.4	V	$I_{OL} = 3.2\ \text{mA}$
V_{IH}	Input HIGH Voltage	2.0		$V_{CC} + 0.5$	V	
V_{IL}	Input LOW Voltage	– 0.5		0.8	V	
I_{LI}	Input Load Current			± 10	μA	$V_{SS} \leq V_I \leq V_{CC}$
I_{LO}	Output Leakage Current			± 10	μA	$V_{CC} \leq V_O \leq V_{SS} + 0.40$
I_{CC}	V_{CC} Supply Current		65	130	mA	$T_A = +25^\circ\text{C}$
			75	150	mA	$T_A = 0^\circ\text{C}$
C_O	Output Capacitance		4	8	pF	$f_c = 1.0\ \text{MHz}$, Inputs = 0V
C_I	Input Capacitance		8	15	pF	
C_{IO}	I/O Capacitance		10	18	pF	

Notes:

- Typical values are for $T_A = 25^\circ\text{C}$, nominal supply voltage and nominal processing parameters.
- Input timing parameters assume transition times of 20 ns or less. Waveform measurement points for both input and output signals are 2.0V for HIGH and 0.8V for LOW, unless otherwise noted.
- Output loading is 1 TTL gate plus 50 pF capacitance, unless otherwise noted.
- The net \overline{IOW} or \overline{MEMW} Pulse width for normal write will be $TCY-100$ ns and for extended write will be $2TCY-100$ ns. The net \overline{IOR} or \overline{MEMR} pulse width for normal read will be $2TCY-50$ ns and for compressed read will be $TCY-50$ ns.
- TDQ is specified for two different output HIGH levels. TDQ1 is measured at 2.0V. TDQ2 is measured at 3.3V. The value for TDQ2 assumes an external 3.3 k Ω pull-up resistor connected from HRQ to V_{CC} .
- DREQ should be held active until DACK is returned.
- DREQ and DACK signals may be active high or active low. Timing diagrams assume the active high mode.
- Output loading on the data bus is 1 TTL gate plus 100 pF capacitance.
- Successive read and/or write operations by the external processor to program or examine the controller must be timed to allow at least 600 ns for the 8237 and at least 400 ns for the 8237-2 as recovery time between active read or write pulses.
- Parameters are listed in alphabetical order.
- Pin 5 is an input that should always be at a logic high level. An internal pull-up resistor will establish a logic high when the pin is left floating. Alternatively, pin 5 may be tied to V_{CC} .

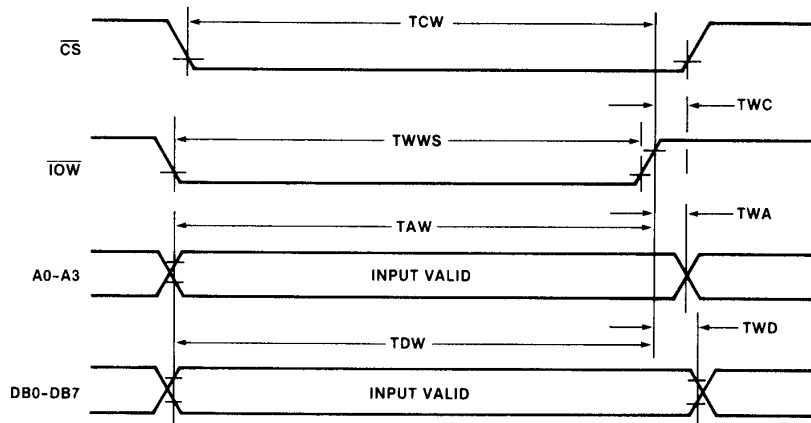
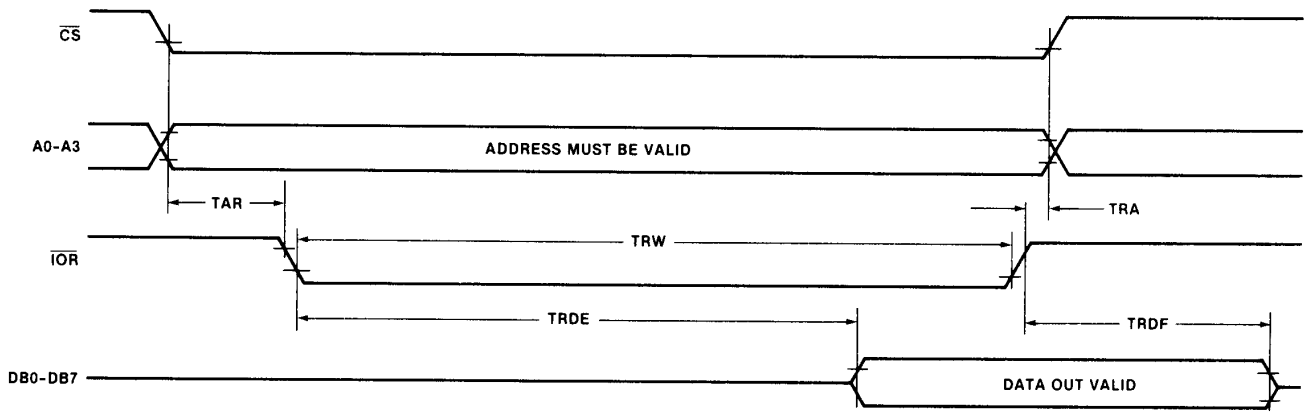
A.C. TEST WAVEFORM

A.C. CHARACTERISTICS: DMA (MASTER) MODET_A = 0°C to 70°C, V_{CC} = 5.0V ± 5%, GND = 0V

Symbol	Parameter	8237		8237-2		Unit
		Min.	Max.	Min.	Max.	
TAEL	AEN HIGH from CLK LOW (S1) Delay Time		300		200	ns
TAET	AEN LOW from CLK HIGH (S1) Delay Time		200		130	ns
TAFAB	ADR Active to Float Delay from CLK HIGH		150		90	ns
TAFC	READ or WRITE Float from CLK HIGH		150		120	ns
TAFDB	DB Active to Float Delay from CLK HIGH		250		170	ns
TAHR	ADR from READ HIGH Hold Time	TCY-100		TCY-100		ns
TAHS	DB from ADSTB LOW Hold Time	50		30		ns
TAHW	ADR from WRITE HIGH Hold Time	TCY-50		TCY-50		ns
TAK	DACK Valid from CLK LOW Delay Time		250		170	ns
	EOP HIGH from CLK HIGH Delay Time		250		170	ns
	EOP LOW to CLK HIGH Delay Time		250		100	ns
TASM	ADR Stable from CLK HIGH		250		170	ns
TASS	DB to ADSTB LOW Setup Time	100		100		ns
TCH	Clock High Time (Transitions ≤ 10 ns)	120		70		ns
TCL	Clock LOW Time (Transitions ≤ 10 ns)	150		50		ns
TCY	CLK Cycle Time	320		200		ns
TDCL	CLK HIGH to READ or WRITE LOW Delay (Note 4)		270		190	ns
TDCTR	READ HIGH from CLK HIGH (S4) Delay Time (Note 4)		270		190	ns
TDCTW	WRITE HIGH from CLK HIGH (S4) Delay Time (Note 4)		200		130	ns
TDQ1	HRQ Valid from CLK HIGH Delay Time (Note 5)		160		120	ns
TDQ2			250		120	ns
TEPS	EOP LOW from CLK LOW Setup Time	60		40		ns
TEPW	EOP Pulse Width	300		220		ns
TFAAB	ADR Float to Active Delay from CLK HIGH		250		170	ns
TFAC	READ or WRITE Active from CLK HIGH		200		150	ns
TFADB	DB Float to Active Delay from CLK HIGH		300		200	ns
THS	HCDA Valid to CLK HIGH Setup Time	100		75		ns
TIDH	Input Data from MEMR HIGH Hold Time	0		0		ns
TIDS	Input Data to MEMR HIGH Setup Time	250		170		ns
TODH	Output Data from MEMW HIGH Hold Time	20		10		ns
TODV	Output Data Valid to MEMW HIGH	200		130		ns
TQS	DREQ to CLK LOW (S1, S4) Setup Time	0		0		ns
TRH	CLK to READY LOW Hold Time	20		20		ns
TRS	READY to CLK LOW Setup Time	100		75		ns
TSTL	ADSTB HIGH from CLK HIGH Delay Time		200		130	ns
TSTT	ADSTB LOW from CLK HIGH Delay Time		140		90	ns

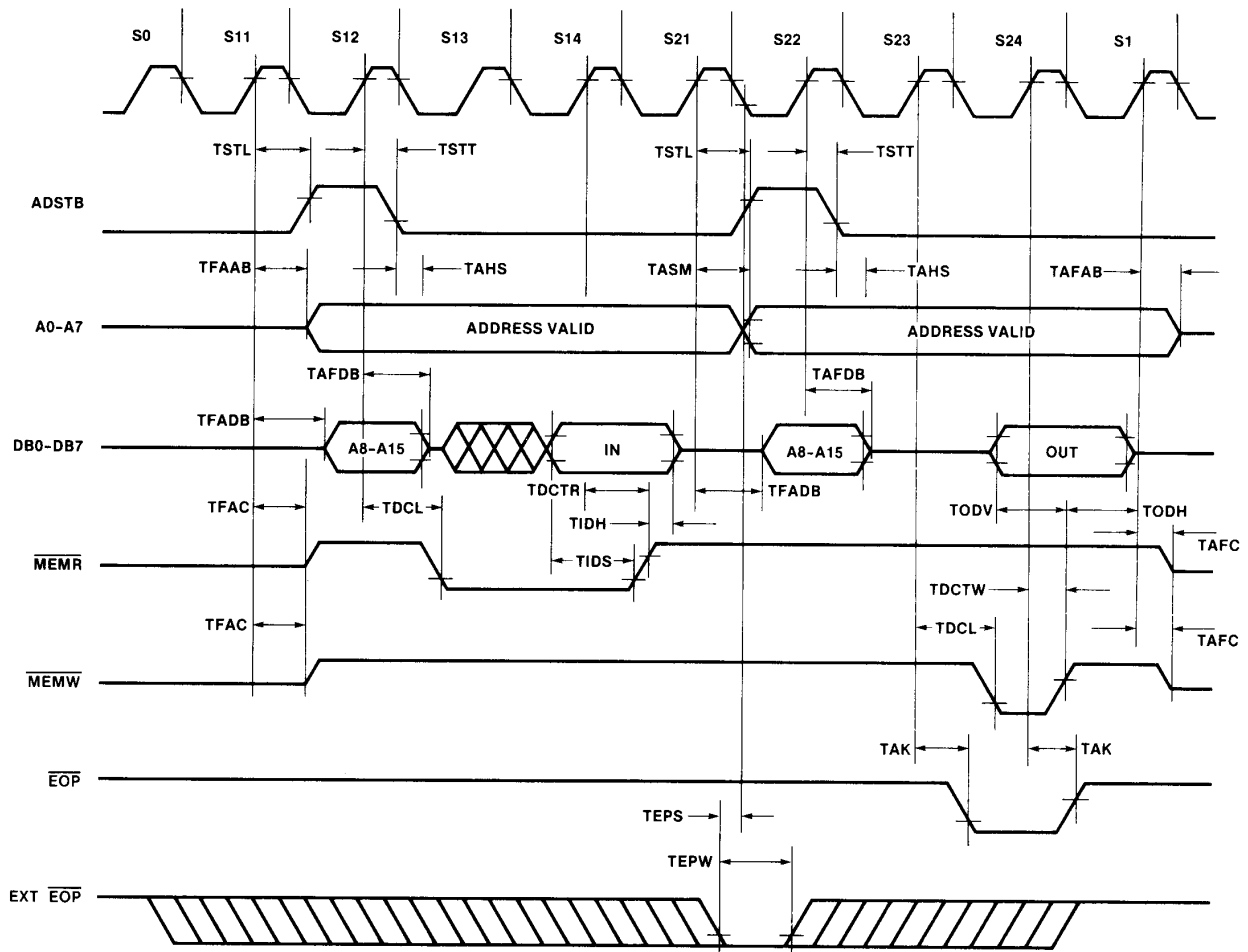
A.C. CHARACTERISTICS: PERIPHERAL (SLAVE) MODET_A = 0°C to 70°C, V_{CC} = 5.0V ± 5%, GND = 0V

Symbol	Parameter	8237		8237-2		Unit
		Min.	Max.	Min.	Max.	
TAR	ADR Valid or \overline{CS} LOW to \overline{READ} LOW	50		50		ns
TAW	ADR Valid to \overline{WRITE} HIGH Setup Time	200		160		ns
TCW	CS LOW to \overline{WRITE} HIGH Setup Time	200		160		ns
TDW	Data Valid to \overline{WRITE} HIGH Setup Time	200		160		ns
TRA	ADR or CS Hold from \overline{READ} HIGH	0		0		ns
TRDE	Data Access from \overline{READ} LOW (Note 8)		200		140	ns
TRDF	DB Float Delay from \overline{READ} HIGH	20	100	0	70	ns
TRSTD	Power Supply HIGH to RESET LOW Setup Time	500		500		μs
TRSTS	RESET to First \overline{IOWR}	2TCY		2TCY		ns
TRSTW	RESET Pulse Width	300		300		ns
TRW	\overline{READ} Width	300		200		ns
TWA	ADR from \overline{WRITE} HIGH Hold Time	20		0		ns
TWC	\overline{CS} HIGH from \overline{WRITE} HIGH Hold Time	20		0		ns
TWD	Data from \overline{WRITE} HIGH Hold Time	30		10		ns
TWWS	Write Width	200		160		ns

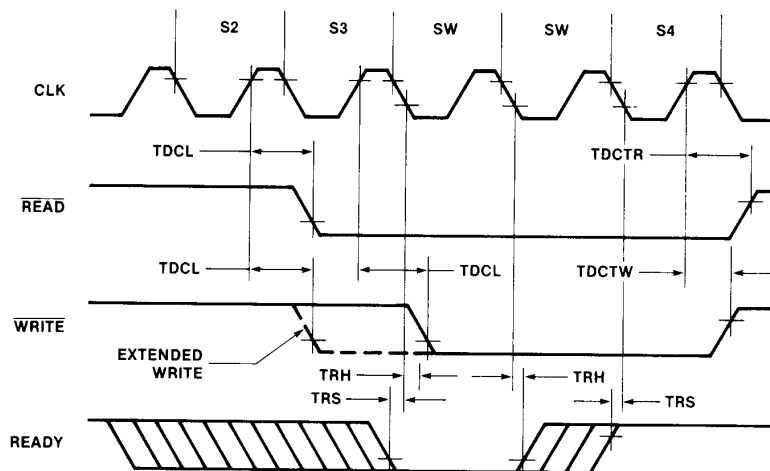
TIMING DIAGRAM #1 — SLAVE MODE WRITE TIMING**TIMING DIAGRAM #2 — SLAVE MODE READ TIMING**



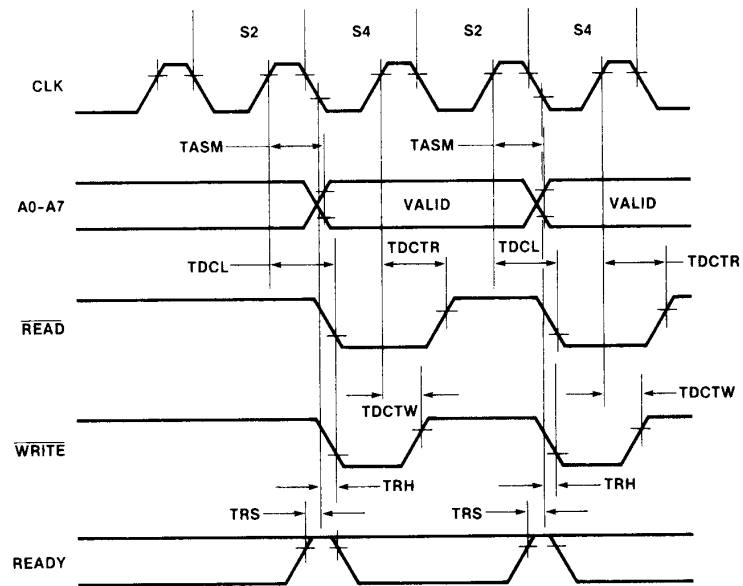
TIMING DIAGRAM #4 — MEMORY TO MEMORY TRANSFER TIMING



TIMING DIAGRAM #5 — READY TIMING



TIMING DIAGRAM #6 — COMPRESSED TRANSFER TIMING



TIMING DIAGRAM #7 — RESET TIMING

