



## 8214 PRIORITY INTERRUPT CONTROL UNIT

- Eight Priority Levels
- Current Status Register
- Priority Comparator
- Fully Expandable
- High Performance (50ns)
- 24-Pin Dual In-Line Package

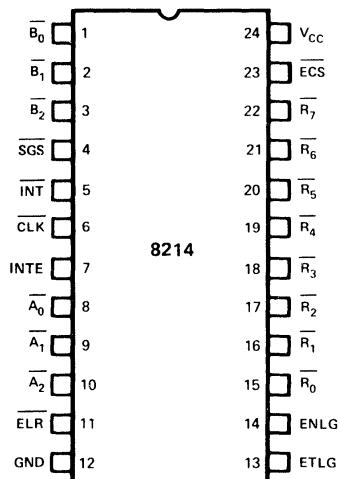
The 8214 is an eight level priority interrupt control unit designed to simplify interrupt driven microcomputer systems.

The PICU can accept eight requesting levels; determine the highest priority, compare this priority to a software controlled current status register and issue an interrupt to the system along with vector information to identify the service routine.

The 8214 is fully expandable by the use of open collector interrupt output and vector information. Control signals are also provided to simplify this function.

The PICU is designed to support a wide variety of vectored interrupt structures and reduce package count in interrupt driven microcomputer systems.

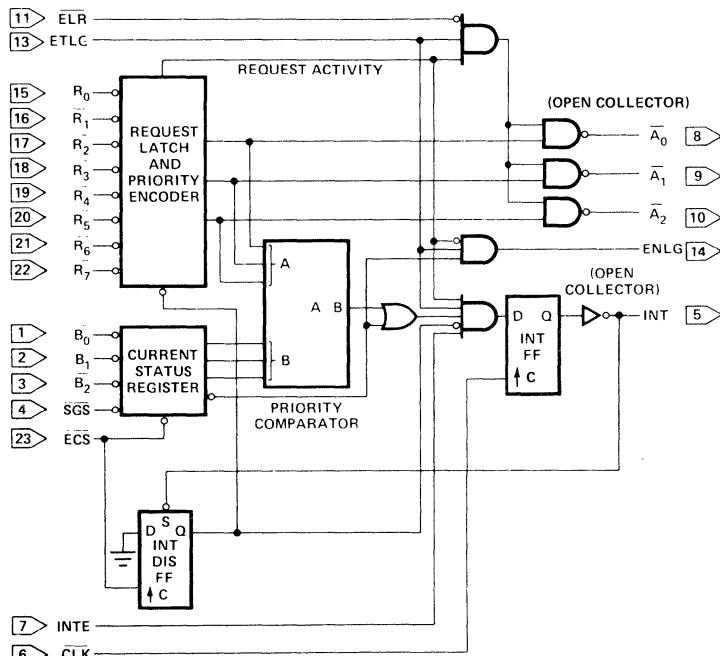
PIN CONFIGURATION



PIN NAMES

INPUTS	
$R_0, R_7$	REQUEST LEVELS (R <sub>7</sub> , HIGHEST PRIORITY)
$B_0, B_2$	CURRENT STATUS
SGS	STATUS GROUP SELECT
ECS	ENABLE CURRENT STATUS
INT	INTERRUPT ENABLE
CLK	CLOCK (INT F/F)
ELR	ENABLE LEVEL READ
ETLG	ENABLE THIS LEVEL GROUP
OUTPUTS:	
$\bar{A}_0, \bar{A}_2$	REQUEST LEVELS
INT	INTERRUPT (ACT. LOW)
ENLG	ENABLE NEXT LEVEL GROUP

LOGIC DIAGRAM



**D.C. AND OPERATING CHARACTERISTICS****ABSOLUTE MAXIMUM RATINGS\***

Temperature Under Bias . . . . .	0°C to 70°C
Storage Temperature . . . . .	-65°C to +150°C
All Output and Supply Voltages . . . . .	-0.5V to +7V
All Input Voltages . . . . .	-1.0V to +5.5V
Output Currents . . . . .	100 mA

\*COMMENT: Stresses above those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

$T_A = 0^\circ\text{C}$  to  $+70^\circ\text{C}$ ,  $V_{CC} = 5\text{V} \pm 5\%$ .

Symbol	Parameter	Limits			Unit	Conditions
		Min.	Typ. <sup>[1]</sup>	Max.		
$V_C$	Input Clamp Voltage (all inputs)			-1.0	V	$I_C = -5\text{mA}$
$I_F$	Input Forward Current: ETLG input all other inputs		-.15 -.08	-0.5 -0.25	mA mA	$V_F = 0.45\text{V}$
$I_R$	Input Reverse Current: ETLG input all other inputs			80 40	$\mu\text{A}$ $\mu\text{A}$	$V_R = 5.25\text{V}$
$V_{IL}$	Input LOW Voltage: all inputs			0.8	V	$V_{CC} = 5.0\text{V}$
$V_{IH}$	Input HIGH Voltage: all inputs	2.0			V	$V_{CC} = 5.0\text{V}$
$I_{CC}$	Power Supply Current			90 130	mA	See Note 2.
$V_{OL}$	Output LOW Voltage: all outputs		.3	.45	V	$I_{OL} = 15\text{mA}$
$V_{OH}$	Output HIGH Voltage: ENLG output	2.4	3.0		V	$I_{OH} = -1\text{mA}$
$I_{OS}$	Short Circuit Output Current: ENLG output	-20	-35	-55	mA	$V_{OS} = 0\text{V}$ , $V_{CC} = 5.0\text{V}$
$I_{CEX}$	Output Leakage Current: $\overline{\text{INT}}$ and $\overline{\text{A}_0 \cdot \overline{\text{A}}_2}$			100	$\mu\text{A}$	$V_{CEX} = 5.25\text{V}$

## NOTES:

1. Typical values are for  $T_A = 25^\circ\text{C}$ ,  $V_{CC} = 5.0\text{V}$ .
2.  $B_0-B_2$ ,  $\overline{SGS}$ ,  $\overline{CLK}$ ,  $\overline{R_0-R_4}$  grounded, all other inputs and all outputs open.

**A.C. CHARACTERISTICS AND WAVEFORMS**  $T_A = 0^\circ\text{C}$  to  $+70^\circ\text{C}$ ,  $V_{CC} = +5\text{V} \pm 5\%$ 

Symbol	Parameter	Limits			Unit
		Min.	Typ. <sup>[1]</sup>	Max.	
$t_{CY}$	$\bar{CLK}$ Cycle Time	80	50		ns
$t_{PW}$	$\bar{CLK}$ , $\bar{ECS}$ , $\bar{INT}$ Pulse Width	25	15		ns
$t_{ISS}$	INTE Setup Time to $\bar{CLK}$	16	12		ns
$t_{ISH}$	INTE Hold Time after $\bar{CLK}$	20	10		ns
$t_{ETCS}^{[2]}$	ETLG Setup Time to $\bar{CLK}$	25	12		ns
$t_{ETCH}^{[2]}$	ETLG Hold Time After $\bar{CLK}$	20	10		ns
$t_{ECCS}^{[2]}$	$\bar{ECS}$ Setup Time to $\bar{CLK}$	80	50		ns
$t_{ECCH}^{[3]}$	$\bar{ECS}$ Hold Time After $\bar{CLK}$	0			ns
$t_{ECRS}^{[3]}$	$\bar{ECS}$ Setup Time to $\bar{CLK}$	110	70		ns
$t_{ECRH}^{[3]}$	$\bar{ECS}$ Hold Time After $\bar{CLK}$	0			ns
$t_{ECSS}^{[2]}$	$\bar{ECS}$ Setup Time to $\bar{CLK}$	75	70		ns
$t_{ECSH}^{[2]}$	$\bar{ECS}$ Hold Time After $\bar{CLK}$	0			ns
$t_{DCS}^{[2]}$	$\bar{SGS}$ and $\bar{B}_0\cdot\bar{B}_2$ Setup Time to $\bar{CLK}$	70	50		ns
$t_{DCH}^{[2]}$	$\bar{SGS}$ and $\bar{B}_0\cdot\bar{B}_2$ Hold Time After $\bar{CLK}$	0			ns
$t_{RCS}^{[3]}$	$\bar{R}_0\cdot\bar{R}_7$ Setup Time to $\bar{CLK}$	90	55		ns
$t_{RCH}^{[3]}$	$\bar{R}_0\cdot\bar{R}_7$ Hold Time After $\bar{CLK}$	0			ns
$t_{ICS}$	$\bar{INT}$ Setup Time to $\bar{CLK}$	55	35		ns
$t_{CI}$	CLK to $\bar{INT}$ Propagation Delay		15	25	ns
$t_{RIS}^{[4]}$	$\bar{R}_0\cdot\bar{R}_7$ Setup Time to $\bar{INT}$	10	0		ns
$t_{RIH}^{[4]}$	$\bar{R}_0\cdot\bar{R}_7$ Hold Time After $\bar{INT}$	35	20		ns
$t_{TRA}$	$\bar{R}_0\cdot\bar{R}_7$ to $\bar{A}_0\cdot\bar{A}_2$ Propagation Delay		80	100	ns
$t_{ELA}$	$\bar{ELR}$ to $\bar{A}_0\cdot\bar{A}_2$ Propagation Delay		40	55	ns
$t_{ECA}$	$\bar{ECS}$ to $\bar{A}_0\cdot\bar{A}_2$ Propagation Delay		100	120	ns
$t_{ETA}$	ETLG to $\bar{A}_0\cdot\bar{A}_2$ Propagation Delay		35	70	ns
$t_{DECS}^{[4]}$	$\bar{SGS}$ and $\bar{B}_0\cdot\bar{B}_2$ Setup Time to $\bar{ECS}$	15	10		ns
$t_{DECH}^{[4]}$	$\bar{SGS}$ and $\bar{B}_0\cdot\bar{B}_2$ Hold Time After $\bar{ECS}$	15	10		ns
$t_{REN}$	$\bar{R}_0\cdot\bar{R}_7$ to ENLG Propagation Delay		45	70	ns
$t_{ETEN}$	ETLG to ENLG Propagation Delay		20	25	ns
$t_{ECRN}$	$\bar{ECS}$ to ENLG Propagation Delay		85	90	ns
$t_{ECSN}$	ECS to ENLG Propagation Delay		35	55	ns

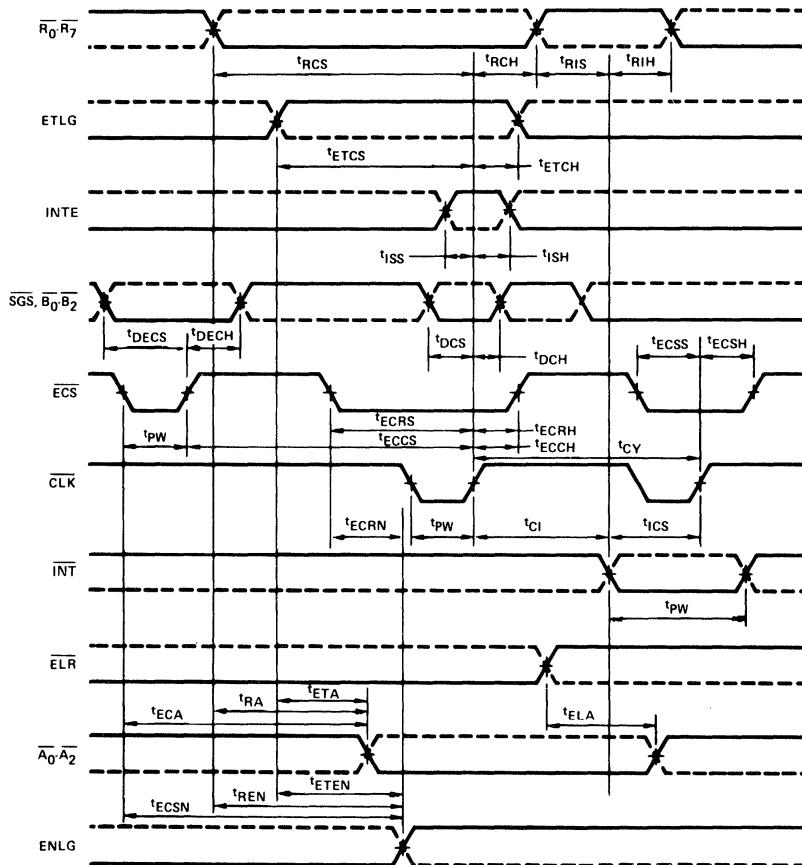
**CAPACITANCE<sup>[5]</sup>**

Symbol	Parameter	Limits			Unit
		Min.	Typ. <sup>[1]</sup>	Max.	
$C_{IN}$	Input Capacitance		5	10	pF
$C_{OUT}$	Output Capacitance		7	12	pF

**TEST CONDITIONS:**  $V_{BIAS} = 2.5\text{V}$ ,  $V_{CC} = 5\text{V}$ ,  $T_A = 25^\circ\text{C}$ ,  $f = 1\text{ MHz}$

NOTE 5. This parameter is periodically sampled and not 100% tested.

## WAVEFORMS



## NOTES:

- (1) Typical values are for  $T_A = 25^\circ C$ ,  $V_{CC} = 5.0V$ .
- (2) Required for proper operation if ISE is enabled during next clock pulse.
- (3) These times are not required for proper operation but for desired change in interrupt flip-flop.
- (4) Required for new request or status to be properly loaded.

## TEST CONDITIONS:

- Input pulse amplitude: 2.5 volts.  
 Input rise and fall times: 5 ns between 1 and 2 volts.  
 Output loading of 15 mA and 30 pf.  
 Speed measurements taken at the 1.5V levels.

## TEST LOAD CIRCUIT

